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PRODUCT FAMILY: SOLO Controllers **Subject:** Temperature control examples Number:AN-LC-009Date issued:Dec-10-2007Revision:First edition

The SOLO controller comes in different flavors. There are versions with analog output, pulse output or relay outputs. The controller to be used in this example is the SOLO SL9696-RRE. Most of the time the clients need to use ON/OFF control or PID control. These 2 examples will show a simple application and will compare the results for learning purposes.

The application note considers a toaster oven of 120 Volt, but the internal control has been bypassed to allow the SOLO controller to regulate the temperature.

The oven has a heating element with a resistance of 11.8 Ohm cold. We have implementing the control thru a solid state relay.

Please see the arrangement below:

We have used other AUTOMATION DIRECT products, namely the adapter FA-ISOCON, a power supply of 12 Volt, and the solid state AD-SSR225-DC, for 10 A rated current.



ON/OFF temperature control

In this example we will use the mentioned SOLO controller to control the temperature of the electrical oven between 50 to 400° F with a relay output. The controller will work in this example as ON/OFF control, using a thermocouple type J.

First, we will set the controller to the factory default condition.

For that, we do the following, after turning the controller ON:

- 2 Press and hold the keys ▲ and ▲ simultaneously for one second. When you let go, the display should show 5Hou in PV and 5FF in SV.
- Cycle power to the controller to reset it to factory default values. All the values defined by the user will be erased. When turning on the controller, the display shows the version of firmware (example **biss**) and the type of controller, in this case, **biss** for 3 seconds.
- **5** The display shows **D** in front of PV and **D** in front to SV.

It is necessary now to go to the **initial configuration mode**:

- Press the SET key for three seconds. Press the key □ until [ErL appears. Press one of the keys △ or □ until the type of control onof appears. Press the SET key in order to accept the value.
- 2 Press the key 🖸 until 5-He appears. HERE will show up. Then press the 🖭 key.
- ③ Press the set key for three seconds. □ Appears in the display. Press one of the keys ▲ or ▲ until the type of thermocouple appears (J in this case). If it is different, select from the table on next page.
- ④ The display shows ☑ in front of SV, and it should be changed in this case to thermocouple J with the key ▲. The press the IT key in order to accept this value.
- 6 Press the state key for less than three seconds to see H=5. Press one of the keys
 ▲ or ▲ to define the hysteresis. Let's leave the value in 0 in this case. Then press the state key.
- 6 Press the key 🖸 until 🖽 appears, Unit of temperature, in the display.
- ⑦ If the display shows ☐ then it should be changed to F (Fahrenheit) with the ▲ key.
- 8 Press the key 🖸 until the parameter EP-H appears, upper limit of the input range.

Thermocouple Type	
Input Temperature Sensor Type	LED Display
Thermocouple TXK type	ヒビビ
Thermocouple U type	
Thermocouple L type	Ŀ
Thermocouple B type	6
Thermocouple S type	5
Thermocouple R type	_
Thermocouple N type	-
Thermocouple E type	Ξ
Thermocouple T type	E
Thermocouple J type	
Thermocouple K type	E
RTD Type	
Input Temperature Sensor Type	LED Display
Platinum Resistance (Pt100)	PE
Platinum Resistance (JPt100)	JPE
Voltage Input Type	
Voltage Input Type	LED Display
0~50mV Analog Input	กีบ
0V~10V Analog Input	L 10
0V~5V Analog Input	5
Current Input Type	
Current Input Type	LED Display
4~20mA Analog Input	584
0~20mA Analog Input	ARC .

9 The display shows 555.5 in front of SV, that it must be changed in this case to 555.6 with the key 1. Then press the key 1 in order to accept this value. If the value of temperature is greater than this selected value, it will create an error.

11 Press the □ key until the display shows □ L, lower limit of the input range. The □ L in front of SV should be changed to 50.0 with the □ key.

12 Then press the **SET** key to accept this value and then press **SET** to return to the operation screen.

O Press the □ key until the displays show □ . Use keys □ or □ to select a
□, which will indicate the degrees directly or a □, the value that will indicate the temperature in tenths of a degree. Then press the □ key to accept this value then press □ to return to the operation screen.

- Press the key 🖸 until the display PV shows = 5. Use the key 🔽 to change the value on the display SV to = 0. Press the key 💷.
- If the temperature shows a small constant offset in the range, you can adjust the reading by pressing the key EE for less than 3 seconds. Press the key □ until you see EPoF. on the display. Use the keys □ or □ to set a positive or negative offset to the actual value of temperature shown by the controller. Then press the key st to accept this value and then press st to go back to the operation screen..

BLB2 and **BLB3** are left as 0, that is, disabled.

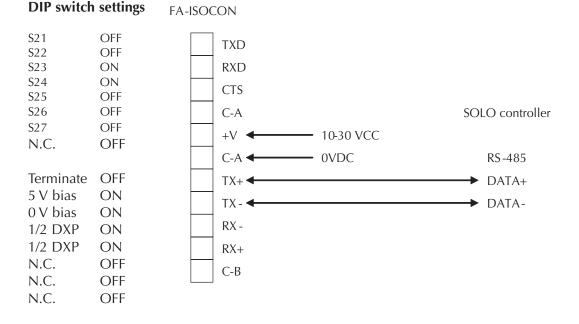
The alarm **SRLB** is left **DFF**.

The parameter **ECSH** will be activated to allow the use of MODBUS RS-485 communications, MODBUS mode **E-52** as **E23**, slave address **E-62 B**, Baud rate **BFS** as **E32**, data lengths **E-6** as 8, parity **B-6**, and stop bits **E-68 B**E as **B**.

Now it is the time to run the controller.

Link the SOLO configuration software to the controller.

In order to monitor the operation we will link the SOLO controller to a PC with the program SLSOFT, and for that we need to use a RS-232 to RS-485 adapter (Normally the PC's do not have a RS-485 port, only RS-232) such as the module FA-ISOCON. It will be connected according to the following diagram:



- 1 Press the key **SET** for 3 seconds to go to the initial Setting mode. The display shows **ERE**.
- 2 Press the key □ until the display shows □5#. Use one of the keys □ or to change the display to ress the key .
- 3 Press the key 🖸 until the display PV shows ☐=54. Use one of the keys 🔽 or 🔼 to change the display to 🕫5000. Press the key 🗺.

- ④ Press the key □ until the display shows □ □ □. Use one of the keys □ or to change the display to 2 (Slave 2). Press the key □.
- 6 Press the key ♀ until the display shows ▷ . Use one of the keys ▼ or ▼ to change the display to □ . Press the key set.
- 6 Press the key 🖸 until the display shows **EFA**. Use one of the keys 🔽 or 🔼 to change the display to 🛙 (bits) . Press the key 💵.
- ⑦ Press the key ☑ until the display shows PFEB. Use one of the keys ☑ or ☑ to change the display to EUEn. Press the key str.
- ⑧ Press the key ☑ until the display shows ☑ □ Use one of the keys ☑ or ☑ to change the display to Ⅰ. Press the key ☑.

The allows to enable three communication between a PC with the software SOLO and the controller. It is assumed that you have already installed the program into your PC. When the program is started, you will see the following screen:



Click the menu **PROTOCOL** in the upper left corner and the adjacent dialog will

pop up, shown as the previous set up.

Adjust the address to **2** (Slave 2) on the set up screen and then click in **Connect**.

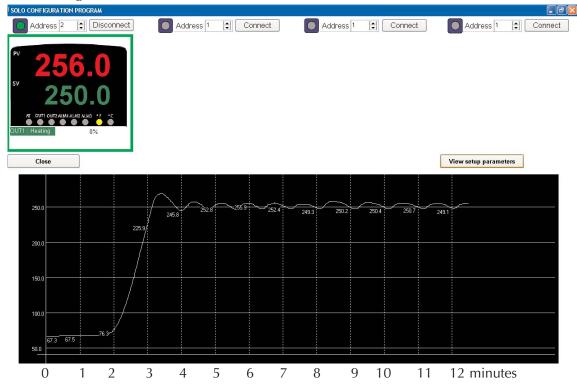
The specific data of the linked controller will be displayed on the screen, as it is shown on the figure of the following page:

COMPORT P	ROTOCOL		X
ComPort	OM PORT S	ETTING	
© COM1 COM2	· · · · · · · · · · · · · · · · · · ·)M5 OCOM7)M6 OCOM8	
Baudrate 2400bps 4800bps	 9600bps 19200bps 	🔿 38400bps	
Parity Bit	💿 Even	🔘 Odd	
Data Bit Length	🔘 8 bits		
Stop Bit Length 1 bit	🔘 2 bits	ок	
Modbus Format	○ RTU		

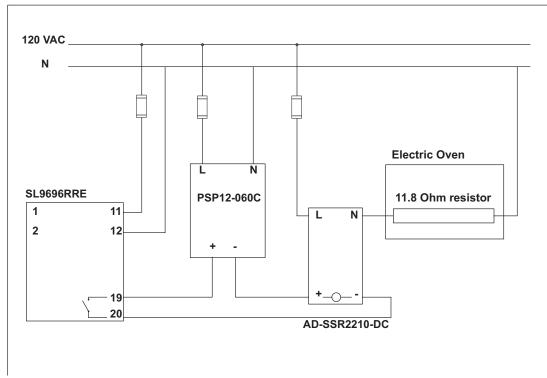
		idress 1 🛟 Co	onnect	Address 1 😫	Connect	Address 1 🔃 Connect
[~] 51.	4					
50 .	0					
	+r +c					
OUT1 : Heating ()	%					
Close	Save to File	Open File	Edit	Ramp/Seak Pattern		PV Monitor
Controller Setup		Control S	etup		Operation	Mode
P3-12 CoSH On-line	Configuration Enable		Control Mode	ON/OFF	1	S RUN/STOP Run
P2-10 Lock Ma	de Unlocked	P3-7 5-8	Heating/Cooling	Heating 🛛		
Input Setup			SV (Set Point)	250.0	Alarm Set	up
P3-1 CoPE Input Ty	ј-Туре	ON-OFF			P3-8 818	Alarm1 0 Alarm Disabled
P3-2 とPUn Unit	F		G Heating Hysteresis	s 0.0		
P2-3 5P Decima Position	Point 1 (***.*)		The using Hysterics.			
P3-3 EP-H Range H	ligh 999.9	P1-15 259	Bead Band	0.0	P3-9 81 8	Alarm2 0 Alarm Disabled
P3-4 EP-L Rangel	ow - 99.9		0 Doud Dund	0.0		
P1-16 とPoF Offset	0.0					
Output1 Setup (Ar	alog Output)				P3-10 RLP	Alarm3 0 Alarm Disabled
	ustment 0					
Р1-17 СсНС High Ad	Gournone					
P1-17 [H] High Ad P1-18 [Lo Low Ad						

When in the **operation mode**, the temperature controller can now initiate the real temperature control if the power has been energized. Adjust the desired temperature SV to 250 degrees and turn on the controller by setting the parameter **FIS** TO **FIG**.

See below the temperature characteristic along the time as seen with the SOLO configuration software.



Wiring diagram



See below the wiring diagram for this specific case.

Comments

The initial temperature was 67.3 degrees F. There was one overshoot at about 3 seconds since the controller output was turned on for 3 minutes continuously on.

After the actual temperature overpasses the desired temperature value, the controller turned OFF the output contact until the temperature dropped below 250 degrees. Immediatelly the output contact closed again to deliver energy to keep the temperature inside the oven close to 250 degrees.

Observe that the controller determines when the actual temperature value has crossed the reference value (the desired value) and this keeps turning on and off the output contact. This works similar to the home control of heating during winter.

This completes this example. In this example we have not considered alarms.

Please also note that we have left a hysteresis value of 0. On other applications it could be necessary to change the values to allow the controller to get a delay before the output contact is turned on after the actual temperature crosses the reference point into the lower temperature.

PID control example

In this example we will use the same temperature control on the electric oven with the same temperature range of 50 to 400° F with a relay output. See the picture of the system on page 1.

Recall that a PID control has an analog output. In this case, the output is in reality a relay, that will open and close in certain period in such a way that when the output is 100% the relay will be closed 100% if the time on the mentioned period. If the output is, let's say, 50%, the output will be on for 50% of the time, and off for the rest os the cycle, being the time proportional to the analog output. This is sometimes called *time proportioning control*.

Set the controller as a **factory default conditions** as explained on page 2.

If you have not done the initial setting, use the procedure to set the thermocouple type, as shown on page 3. If done, just change the **EEEE** parameter to PID.

Make a MODBUS communication link from a PC with a SOLO configuration program to the SOLO controller. See the instructions on page 4.

Now you can set up the PID loop.

There are 4 parameter groups for storing control values for the PID loop, namely **PEGD** to **PEGD**.

Press the key SET for more than 3 seconds. Press the key I until you see
 EterL. Use one of the keys I or I to change the display to II.
 Press the SET key to accept this value.

Since at this point you are doing time proportioning control, the **HEPE** value is important. The default value may be fine but you should take care of the proper value there. The HTPD value is the cycle period (default is 0.5 second) and this is the value we are working with in this example.

- Press the key I until you see I to should show up HEBE. Then press the key I. You can also set the values of these parameters from the screen of the configuration software SOLO.
- The controller should be now in Operating mode. Adjust the temperature set point to 250 degrees F.
- ④ Observe that the control output (the relay) will begin to close and open on the period defined. Press the key st and set the controller to FUF. Then search № on the display with the key CP.

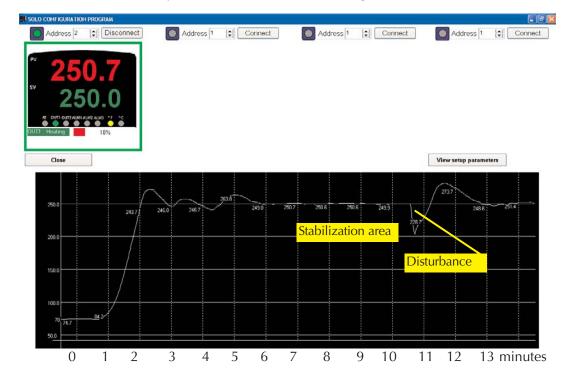
5 Press the key **A** and press **S** to start the auto tuning.

Observe the temperature curve in the figure at the bottom of the next page.

Address 2 🔃 Disconne	ict 🛛 🔘 Addre	ss 1 🔃 C	onnect	Address 1	 	Connect	Address	1 🗘 Co	onnect
250.0 250.0 rt cott cott Anti Alico Auto 11 - 12 UTTE Heading 24%									
Close Save t	o File Op	en File		Ramp/Soak Patt	lern .	Operation	PV Monit	or	
ontroller Setup 3-12 CoSH On-line Configurati	on Enable	P3-5	Control Mode	PID	4	Operation P2-1	S RUN/STOP	Run	*
		1.81709							
2-10 Lock Mode	Unlocked 🛛	P3-7 5-	Heating/Cooling	Heating	6	P1-1 8	Auto-tuning	Stop	3
put Setup			SV (Set Point)	250.0		Alarm Set	up		
3-1 COPE Input Type	J-Type	PID Para	neter			P3-8 818	Alarm1 0 Al	arm Disabled	×
3-2 290 Unit	F		PID Parameters	0	Y				
2-3 Decimal Point Position	1 (***.*)		Target SV	250.0					
	400.0		Proportion Band	24.0		P3-9 81.6	Alarm2 0 Al	arm Disabled	*
3-3 EP-H Range High	400.0								
	50.0	P1-5	Integral Time	28					
3-4 EP-L Range Low	Construction of the second sec		Integral Time	29 7					
3-4 EP-L Range Low 1-16 EPoF Offset	50.0 0.0		Derivative Time					Disabled	
3-4 EP=L Range Low 1-16 EPoF Offset Output1 Setup (Analog O	50.0 0.0	P1-6 P1-7	Derivative Time	7		P3-10 RL f	Alarm3 0 Al	arm Disabled	×
3-4 EP-L Range Low	50.0 0.0	P1-6 P1-7	Derivative Time	7 33.3		P3-10 RL1	Alarm3 0 A	arm Disabled	M

6 The LED AT will begin to blink to indicate that the controller is tuning the loop. When the tuning is completed, the LED AT is turned OFF and the controller determines the values in (24), (29) and (7),

This initiates the temperature control. Observe the figure below.



Note on the temperature curve, on the time 2 to 6 minutes, there are temperature oscillations around the set point. This is a elapsed time when the controller is doing the automatic tuning. When the LED **AT** is turned OFF, close to 6 minutes, the temperature is stabilized.

We provoked a disturbance on about 10.5 minutes by fully opening the oven door, which caused a decrease in temperature. Then, following that, the door is closed and the controller applies heat to correct the temperature. There is an overshoot at about 12 minutes, that is corrected after about 3 minutes and the temperature is stable again.

Naturally, when the oven door is closed, the temperature can be kept very close to the set point and the controller only needs to create small adjustments applying heat to keep the value in 250 degrees.

In order to test the controller in harsher conditions, let's open the door about 5%, to create more release of heat or simulate that there is more heat consumed. See the figure below.

Observe that the output of the controller becomes 35%. This means that, in the period of 20 seconds of the cycle, the controller output control contact has been closed for 7 seconds and (35% of 20 seconds) on each cycle and has been maintened open for 13 seconds.

This is the specific case on this oven. Obviously, in your case, this will be different..

