

Product Family: GS Drives and GSOFT

Subject: PID tuning with GSOFT software PID utility

Number: AN-GS-011

Date Issued: 08/01/03

Revision: Original



Drive: Software: PC: Cable: Various GS series GSOFT software Standard PC GS-232CBL



Preliminary

The PID tuning utility on GSOFT drive configuration software is very important for the proper tuning of PID loops utilizing the onboard PID control of the drive. In the past users would have to hook up an external chart recorder to tune a loop precisely. Today this approach, although viable, is cumbersome. With GSOFT's PID tuning utility, you have the best of both worlds, precision and practicality.





your application.

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CS AC DRIVE CONFIGURATION SOFTWARE CORRE-FILE DRIVE VIEW UTILITIES WINDOW HELP _ 8 × × Select An Action: Start New Configuration 2. Select drive model and new C Open Existing Configuration C Quick Start Configuration configuration name. C Upload Settings From Drive Close Project Navigator Go × GS Series Drive: GS2-22P0 (230 1ph/3ph 2.0 HP) rev. 103 💌 OK New configuration name: PID test set-up Cancel C:\ Browse Select a path to where you want to store your drive configuration: • 0ff-Line Drive Status - Offline [第START] | ⑧ 図 図 図 1 月 | 〒VIRTUAL... | ◎INBOX+... | ■ TEAMW... | ▼SIERRA... | ○C:\MY... | ■]GSSof... | 📧 GS A... | ◎ ③ ● ③ → ◎ ● ③ → ◎ ● ③ → ◎ ● ③ → ◎ ● CS CS AC DRIVE CONFIGURATION SOFTWARE _ 8 × D • 🖉 🔳 🗰 🕄 🙂 🖉 🕸 🖉 🖉 × P 0.xx P 1.xx P 2.xx P 3.xx P 4.xx P 5.xx P 6.xx P 7.xx P 8.xx P 9.xx MOTOR PARAMETERS P0.00 - P0.04 • P0.00 - Motor Nameplate Voltage 240 P0.01 - Motor Nameplate Amps 7.0 P0.02 - Motor Base Frequency 60 • 1750 P0.03 - Motor Base RPM 1750 P0.04 - Motor Maximum RPM 🛎 🖬 🗟 🕱 New File operation started 8/4/2003 9:38:07 AM. File Save operation started 8/4/2003 9:38:10 AM. File Save operation completed 8/4/2003 9:38:14 AM. New File operation completed 8/4/2003 9:38:15 AM. Red label indicates value different fr Minimize Drive Status - Offline 😝 Off-Line 🔹 Start | 🖉 🔯 🖄 🔀 | 🚰 Virtual... 🔯 Indox-... | 📕 TeamW... 🗖 Sierra ... | 🔤 C:\My... | 🗟 GSSof... | 📴 GSSof... | 📴 GSSof... | 🕼 😵 🔆 🏷 🏷 🕸 🕮 9:38 AM



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GS	CONNECTION SET	TINGS	×
	Node Address Of Drive:	1	
	PC Com Port:	Com1	•
	Baud Rate	9600	•
	Protocol:	7, N, 2, MODBUS ASCII	•
	Connect Dis	sconnect Close	

3. Connect to drive over serial interface.

65 Detailed Config - Current Drive Model = C	S2-22P0		
P 0.xx P1.xx P2.xx P3.xx P4.xx P5.xx P6.xx	P7.xx P8.xx P9.xx		
MOTOR F	ARAMETERS		
P0.00 - P0.04			
P0.00 - Motor Nameplate Voltage	230		
P0.01 - Motor Nameplate Amps	7		
P0.02 - Motor Base Frequency	60		
P0.03 - Motor Base RPM	1750		
P0.04 - Motor Maximum RPM	2000		
4.0 Configure drive parameters to application needs. Refer to chapter 4 of GS2 manual.			
Red label indicates value different from Parameter's default. Done			



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DETAILED CONFIG - CURRENT DRIVE MODEL = GS2-2	2P0
P0.xx P1.xx P2.xx P3.xx P4.xx P5.xx P6.xx P7.xx	P 8.xx P 9.xx
RAME	PS []
P1.00 - P1.11 P1.12 - P1.22	
P1.00 - Stop Methods	01: Coast To Stop
P1.01 - Acceleration Time 1	40 4 1 In this application a coast to
P1.02 - Deceleration Time 1	4.1 In this application a coast to
P1.03 - Accel S-curve	increased acceleration and
P1.04 - Decel S-curve	deceleration times of 40 +
P1.05 - Acceleration Time 2	seconds.
P1.06 - Deceleration Time 2	30
P1.07 - Method For 2nd Acc/Decel	00: RMP2 From Terminal
P1.08 - Accel 1 To Accel 2 Frequency Transition	
P1.09 - Decel 1 To Decel 2 Frequency Transition	
P1.10 - Skip Frequency 1	
P1.11 - Skip Frequency 2	
Red label indicates value different from Parameter's defau	ult. Done
C DETAILED CONFIG - CURRENT DRIVE MODEL = GS2-	22P0 X
(P0xx) P1xx) P2xx P3xx) P4xx) P5xx) P6xx) P7	xX P 8 xx P 9 xx
VOLTS / HERT	Z SETTINGS
P2.00 - P2.08	
P2.00 - Volts / Hertz Settings	00: General Purpose
P2.01 - Slip Compensation	
P2.02 - Auto-Torque Boost	6 4.2 It is advisable to use a
P2.03 - Not used for selected drive/rev.	general-purpose volts/hertz
P2.04 - Mid-Point Frequency	set-up to start with. It will
P2.05 - Mid-Point Voltage	accommodate the majority of
P2.06 - Min. Output Frequency	applications for both constant
P2.07 - Min. Output Voltage	and variable torque.
P2.08 - PWM Carrier Frequency	12



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DETAILED CONFIG-CURRENT DRIVE MODEL = GS	2-22P0
-0.xx F1.xx F2.xx F3.xx F4.xx F3.xx F0.xx F0.xx	ABAMETERS
P4.00 - P4.12	
P4.00 - Source Of Frequency Command	00: Keypad Potentiometer
P4.01 - Analog Input Offset Polarity	00: No Offset
P4.02 - Analog Input Offset	0
P4.03 - Analog Input Gain	100
P4.04 - Analog Input Reverse Motion Enable	00: Forward Motion Only
P4.05 - Loss Of ACI Signal	00: Decelerate to 0Hz
P4.06 - Not used for selected drive/rev.	
P4.07 - Not used for selected drive/rev.	
P4.08 - Not used for selected drive/rev.	
P4.09 - Not used for selected drive/rev.	
P4.10 - Not used for selected drive/rev.	
	00: Frequency Hz
P4.11 - Analog Output Signal	
P4.11 - Analog Output Signal P4.12 - Analog Output Gain Red label indicates value different from Parameter's d	IOO Done
P4.11 - Analog Output Signal P4.12 - Analog Output Gain Red label indicates value different from Parameter's d DETAILED CONFIG - CURRENT DRIVE MODEL = GS P0.xx \ P1.xx \ P2.xx \ P3.xx \ P4.xx \ P5.xx \ P6.xx \ P	100 lefault. Done 52-22P0 7.xx P 8.xx P9.xx PID
P4.11 - Analog Output Signal P4.12 - Analog Output Gain Red label indicates value different from Parameter's d DETAILED CONFIG - CURRENT DRIVE MODEL = G9 P0.xx \P1.xx \P2.xx \P3.xx \P4.xx \P5.xx \P6.xx \P P7.00 - P7.11 \P7.12 - P7.23 \P7.2	100 lefault. Done 52-22P0 7.xx P 8.xx P 9.xx PID 24-P7.27
P4.11 - Analog Output Signal P4.12 - Analog Output Gain Red label indicates value different from Parameter's d DETAILED CONFIG - CURRENT DRIVE MODEL = GS P0.xx \[P1.xx \] P2.xx \] P3.xx \[P4.xx \] P5.xx \] P6.xx \] P P7.00 - P7.11 [P7.12 - P7.23 P7.2 P7.00 - Input Terminal For PID Feedback	IOO Done S2-22PO 7.xx P 8.xx P9.xx PID 24 - P7.27 O2: Input Neg PID Feedback, PV From ACI Image: Content of the second se
P4.11 - Analog Output Signal P4.12 - Analog Output Gain Red label indicates value different from Parameter's d DETAILED CONFIG - CURRENT DRIVE MODEL = GS P0.xx \P1.xx \P2.xx \P3.xx \P4.xx \P5.xx \P6.xx \P P7.00 - P7.11 \P7.12 - P7.23 P7.2 P7.00 - Input Terminal For PID Feedback P7.01 - PV 100% Value	100 lefault. Done 52-22P0 7.xx P 8.xx P1D 24 - P7.27 02: Input Neg PID Feedback, PV From ACI 100
P4.11 - Analog Output Signal P4.12 - Analog Output Gain Red label indicates value different from Parameter's d DETAILED CONFIG - CURRENT DRIVE MODEL = GS P0.xx P1.xx P2.xx P3.xx P4.xx P5.xx P6.xx P P7.00 - P7.11 P7.12 - P7.23 P7.2 P7.00 - Input Terminal For PID Feedback P7.01 - PV 100% Value P7.02 - PID Setpoint Source	100 lefault. Done 52-22P0 * 7.xx P 8.xx P9.xx P1D 24 - P7.27 02: Input Neg PID Feedback, PV From ACI 100 00: Keypad
P4.11 - Analog Output Signal P4.12 - Analog Output Gain Red label indicates value different from Parameter's d DETAILED CONFIG - CURRENT DRIVE MODEL = GS P0.xx P1.xx P2.xx P3.xx P4.xx P5.xx P6.xx P P7.00 - P7.11 P7.12 - P7.23 P7.2 P7.00 - Input Terminal For PID Feedback P7.01 - PV 100% Value P7.02 - PID Setpoint Source P7.03 - Not used for selected drive/rev.	100 lefault. Done S2-22P0 PID 24 - P7.27 02: Input Neg PID Feedback, PV From ACI 100 00: Keypad
P4.11 - Analog Output Signal P4.12 - Analog Output Gain Red label indicates value different from Parameter's d DETAILED CONFIG - CURRENT DRIVE MODEL = GS P0.xx P1.xx P2.xx P3.xx P4.xx P5.xx P6.xx P P7.00 - P7.11 P7.12 - P7.23 P7.2 P7.00 - Input Terminal For PID Feedback P7.01 - PV 100% Value P7.02 - PID Setpoint Source P7.03 - Not used for selected drive/rev. P7.04 - Not used for selected drive/rev.	IOO Image: Default. Done S2-22PO PID 24 - P7.27 IOD IOO IOO <t< td=""></t<>
P4.11 - Analog Output Signal P4.12 - Analog Output Gain Red label indicates value different from Parameter's d DETAILED CONFIG - CURRENT DRIVE MODEL = GS P0.xx \P1.xx \P2.xx \P3.xx \P4.xx \P5.xx \P6.xx \P P7.00 - P7.11 P7.12 - P7.23 P7.2 P7.00 - Input Terminal For PID Feedback P7.01 - PV 100% Value P7.02 - PID Setpoint Source P7.03 - Not used for selected drive/rev. P7.04 - Not used for selected drive/rev. P7.05 - Not used for selected drive/rev.	IOD Iefault. Done S2-22PO Done PID Done Q2-P7.27 D2: Input Neg PID Feedback, PV From ACI ▼ IOD DONE DONE Q2: Input Neg PID Feedback, PV From ACI ▼ IOD DONE DONE Q2: Input Neg PID Feedback, PV From ACI ▼ IOD DONE DONE IOD DONE DONE Q2: Input Neg PID Feedback, PV From ACI ▼ IOD DONE DONE IOD DONE DONE DONE IOD DONE <t< td=""></t<>
P4.11 - Analog Output Signal P4.12 - Analog Output Gain Red label indicates value different from Parameter's d DETAILED CONFIG - CURRENT DRIVE MODEL = GS P0.xx P1.xx P2.xx P3.xx P4.xx P5.xx P6.xx P P7.00 - P7.11 P7.12 - P7.23 P7.2 P7.00 - Input Terminal For PID Feedback P7.01 - PV 100% Value P7.02 - PID Setpoint Source P7.03 - Not used for selected drive/rev. P7.04 - Not used for selected drive/rev. P7.05 - Not used for selected drive/rev. P7.06 - Not used for selected drive/rev.	IOD International state Done Done Done S2-22PO Done PID Done Q1-P7.27 D2: Input Neg PID Feedback, PV From ACI Image: Comparison of the picture Q2-P7.27 D2: Input Neg PID Feedback, PV From ACI Image: Comparison of the picture Q2-P7.27 D2: Input Neg PID Feedback, PV From ACI Image: Comparison of the picture Q3-P7.27 D2: Input Neg PID Feedback, PV From ACI Image: Comparison of the picture Q4-P7.27 D2: Input Neg PID Feedback, PV From ACI Image: Comparison of the picture Q4-P7.27 D2: Input Neg PID Feedback, PV From ACI Image: Comparison of the picture Q4-P7.27 D2: Input Neg PID Feedback, PV From ACI Image: Comparison of the picture Q4-P7.27 D2: Input Neg PID Feedback, PV From ACI Image: Comparison of the picture Q5-P7.27 D2: Input Neg PID Feedback, PV From ACI Image: Comparison of the picture Q5-P7.27 D2: Input Neg PID mode P7.00 must be in the picture Image: Comparison of the picture Q5-P7.27 D3-P7.00 must initially be set to 00 until the utility is launched. Then the parameter must be picture
P4.11 - Analog Output Signal P4.12 - Analog Output Gain Red label indicates value different from Parameter's d DETAILED CONFIG - CURRENT DRIVE MODEL = GS P0.xx \P1.xx \P2.xx \P3.xx \P4.xx \P5.xx \P6.xx \P P7.00 - P7.11 P7.12 - P7.23 P7.2 P7.00 - Input Terminal For PID Feedback P7.01 - PV 100% Value P7.02 - PID Setpoint Source P7.03 - Not used for selected drive/rev. P7.04 - Not used for selected drive/rev. P7.05 - Not used for selected drive/rev. P7.06 - Not used for selected drive/rev. P7.07 - Not used for selected drive/rev.	IOD Iefault. Done S2-22PO Done 7.xx P8.xx P9.xx PID Done 24-P7.27 D2: Input Neg PID Feedback, PV From ACI Image: Comparison of the provided method method of the provided method
P4.11 - Analog Output Signal P4.12 - Analog Output Gain Red label indicates value different from Parameter's d DETAILED CONFIG - CURRENT DRIVE MODEL = GS P0.xx P1.xx P2.xx P3.xx P4.xx P5.xx P6.xx P P7.00 - P7.11 P7.12 - P7.23 P7.2 P7.00 - Input Terminal For PID Feedback P7.01 - PV 100% Value P7.02 - PID Setpoint Source P7.03 - Not used for selected drive/rev. P7.05 - Not used for selected drive/rev. P7.06 - Not used for selected drive/rev. P7.07 - Not used for selected drive/rev. P7.08 - Not used for selected drive/rev.	IOD Implementation Done S2-22PO Done <
P4.11 - Analog Output Signal P4.12 - Analog Output Gain Red label indicates value different from Parameter's d DETAILED CONFIG - CURRENT DRIVE MODEL = GS P0.xx P1.xx P2.xx P3.xx P4.xx P5.xx P6.xx P P7.00 - P7.11 P7.12 - P7.23 P7.2 P7.00 - Input Terminal For PID Feedback P7.01 - PV 100% Value P7.02 - PID Setpoint Source P7.03 - Not used for selected drive/rev. P7.04 - Not used for selected drive/rev. P7.05 - Not used for selected drive/rev. P7.06 - Not used for selected drive/rev. P7.07 - Not used for selected drive/rev. P7.08 - Not used for selected drive/rev. P7.09 - Not used for selected drive/rev.	ID0 I
P4.11 - Analog Output Signal P4.12 - Analog Output Gain Red label indicates value different from Parameter's d DETAILED CONFIG - CURRENT DRIVE MODEL = GS P0.xx P1.xx P2.xx P3.xx P4.xx P5.xx P6.xx P P7.00 - P7.11 P7.12 - P7.23 P7.2 P7.00 - Input Terminal For PID Feedback P7.01 - PV 100% Value P7.02 - PID Setpoint Source P7.03 - Not used for selected drive/rev. P7.04 - Not used for selected drive/rev. P7.05 - Not used for selected drive/rev. P7.06 - Not used for selected drive/rev. P7.07 - Not used for selected drive/rev. P7.08 - Not used for selected drive/rev. P7.09 - Not used for selected drive/rev. P7.10 - Keypad PID Setpoint	IOD Done Done S2-22PO 7.xx P8.xx P9.xx PID 24-P7.27 © 21 Input Neg PID Feedback, PV From ACI O A.3 To run in PID mode P7.00 must be in 0 OO 00: Keypad 4.3 To run in PID mode P7.00 must be in 0 O 100 PID 100 PT.00 must initially be set to 00 until the utility is launched. Then the parameter mu be changed to 01 or 02 manually or through the download feature. 0 0
P4.11 - Analog Output Signal P4.12 - Analog Output Gain Red label indicates value different from Parameter's d DETAILED CONFIG - CURRENT DRIVE MODEL = GS P0.xx \[P1.xx] P2.xx] P3.xx] P4.xx] P5.xx] P6.xx] P P7.00 - P7.11 [P7.12 - P7.23 P7.2 P7.00 - Input Terminal For PID Feedback P7.01 - PV 100% Value P7.02 - PID Setpoint Source P7.03 - Not used for selected drive/rev. P7.04 - Not used for selected drive/rev. P7.05 - Not used for selected drive/rev. P7.06 - Not used for selected drive/rev. P7.07 - Not used for selected drive/rev. P7.08 - Not used for selected drive/rev.	IOD IDD IDD </td



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PID tuning utility window:







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